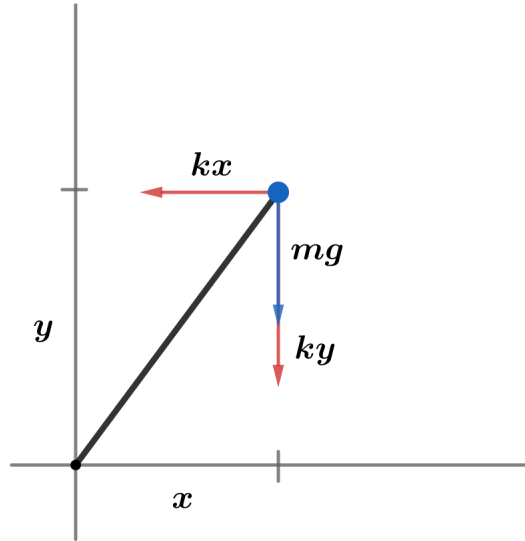


Exercise 4.22

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a) Suppose the mass is located at (x, y) . We always have gravity and we can decompose the spring force along the axes. Applying $F = ma$,

$$m\ddot{x} = -kx$$

$$m\ddot{y} = -ky - mg$$

Defining $\omega = \sqrt{\frac{k}{m}}$,

$$\ddot{x} + \omega^2 x = 0$$

$$\ddot{y} + \omega^2 y = -g$$

The general solution for x is

$$x = A_x \sin(\omega t + \phi_x)$$

For y , we can guess $y = \alpha$ as a particular solution

$$0 + \omega^2 \alpha = -g$$

$$\alpha = -\frac{g}{\omega^2}$$

so the general solution is

$$y = y_g + y_p = A_y \sin(\omega t + \phi_y) - \frac{g}{\omega^2}$$

We are given initial conditions

$$\begin{aligned}x(0) &= y(0) = 0 \\ \dot{x}(0) &= v_0 \cos \theta \\ \dot{y}(0) &= v_0 \sin \theta\end{aligned}$$

Thus,

$$\begin{aligned}x(0) &= A_x \sin \phi_x = 0 \\ \dot{x}(0) &= \omega A_x \cos \phi_x = v_0 \cos \theta \\ \phi_x &= 0 \\ A_x &= \frac{v_0 \cos \theta}{\omega}\end{aligned}$$

so

$$\boxed{x(t) = \frac{v_0 \cos \theta}{\omega} \sin \omega t}$$

We also have

$$\begin{aligned}y(0) &= A_y \sin \phi_y - \frac{g}{\omega^2} = 0 \\ \dot{y}(0) &= \omega A_y \cos \phi_y = v_0 \sin \theta \\ A_y \sin \phi_y &= \frac{g}{\omega^2} \\ A_y \cos \phi_y &= \frac{v_0 \sin \theta}{\omega}\end{aligned}$$

$$\begin{aligned}A_y &= \sqrt{\left(\frac{g}{\omega^2}\right)^2 + \left(\frac{v_0 \sin \theta}{\omega}\right)^2} \\ \tan \phi_y &= \frac{g}{\omega v_0 \sin \theta}\end{aligned}$$

so

$$\boxed{y(t) = \sqrt{\left(\frac{g}{\omega^2}\right)^2 + \left(\frac{v_0 \sin \theta}{\omega}\right)^2} \sin \left[\omega t + \arctan \left(\frac{g}{\omega v_0 \sin \theta} \right) \right] - \frac{g}{\omega^2}}$$

b) For small ω ,

$$x(t) = \frac{v_0 \cos \theta}{\omega} \sin \omega t \approx \frac{v_0 \cos \theta}{\omega} (\omega t) = v_0 t \cos \theta$$

$$y(t) = A_y \sin(\omega t + \phi_y) - \frac{g}{\omega^2} = A_y (\sin \omega t \cos \phi_y + \cos \omega t \sin \phi_y) - \frac{g}{\omega^2}$$

Define $r = g/\omega v_0 \sin \theta$:

$$\cos \phi_y = \cos \arctan r = \frac{1}{\sqrt{r^2 + 1}} \approx \frac{1}{r}$$

$$\sin \phi_y = \sin \arctan r = \frac{r}{\sqrt{r^2 + 1}} \approx 1$$

Then

$$y(t) = A_y \left[(\sin \omega t) \left(\frac{1}{r} \right) + (\cos \omega t) (1) \right] - \frac{g}{\omega^2} \approx A_y \left[(\omega t) \left(\frac{1}{r} \right) + \left(1 - \frac{\omega^2 t^2}{2} \right) (1) \right] - \frac{g}{\omega^2}$$

Note that

$$A_y = \frac{v_0 \sin \theta}{\omega} \sqrt{\left(\frac{g}{\omega v_0 \sin \theta} \right)^2 + 1} = \frac{v_0 \sin \theta}{\omega} \sqrt{r^2 + 1} \approx \frac{v_0 \sin \theta}{\omega} r$$

Thus, combining all terms

$$y(t) = \frac{v_0 \sin \theta}{\omega} r \left(\frac{\omega t}{r} + 1 - \frac{\omega^2 t^2}{2} \right) - \frac{g}{\omega^2}$$

$$y(t) = \frac{g}{\omega^2} \left(\frac{\omega^2 v_0 t \sin \theta}{g} + 1 - \frac{\omega^2 t^2}{2} \right) - \frac{g}{\omega^2}$$

$$y(t) = v_0 t \sin \theta - \frac{gt^2}{2}$$

Hence, small ω corresponds to $r \gg 1$:

$$\frac{g}{\omega v_0 \sin \theta} \gg 1$$

$$\boxed{\omega \ll \frac{g}{v_0 \sin \theta}}$$

For large ω ,

$$x(t) = \frac{v_0 \cos \theta}{\omega} \sin \omega t$$

$$y(t) = A_y \sin(\omega t + \phi_y) - \frac{g}{\omega^2} = A_y (\sin \omega t \cos \phi_y + \cos \omega t \sin \phi_y) - \frac{g}{\omega^2}$$

$$\cos \phi_y = \cos \arctan r = \frac{1}{\sqrt{r^2 + 1}} \approx 1$$

$$\sin \phi_y = \sin \arctan r = \frac{r}{\sqrt{r^2 + 1}} \approx r$$

$$A_y = \frac{v_0 \sin \theta}{\omega} \sqrt{r^2 + 1} \approx \frac{v_0 \sin \theta}{\omega}$$

Thus, combining all terms

$$y(t) \approx \frac{v_0 \sin \theta}{\omega} (\sin \omega t (1) + \cos \omega t (r)) - \frac{g}{\omega^2} = \frac{v_0 \sin \theta}{\omega} (\sin \omega t + r \cos \omega t - r)$$

$$y(t) \approx \frac{v_0 \sin \theta}{\omega} \sin \omega t$$

Hence, large ω corresponds to $r \ll 1$:

$$\frac{g}{\omega v_0 \sin \theta} \ll 1$$

$$\boxed{\omega \gg \frac{g}{v_0 \sin \theta}}$$

c) We want the projectile to hit the ground when it is moving straight downward:

$$y = 0$$

$$\dot{x} = 0$$

so

$$y(t) = A_y \sin(\omega t + \phi_y) - \frac{g}{\omega^2} = A_y(\sin \omega t \cos \phi_y + \cos \omega t \sin \phi_y) - \frac{g}{\omega^2} = 0$$

and

$$\dot{x}(t) = v_0 \cos \theta \cos \omega t = 0 \rightarrow \cos \omega t = 0, \sin \omega t = 1$$

Substituting these conditions into the first equation,

$$A_y((1) \cos \phi_y + (0) \sin \phi_y) - \frac{g}{\omega^2} = 0$$

Substituting A_y ,

$$\left(\frac{v_0 \sin \theta}{\omega} \sqrt{r^2 + 1} \right) \cos \phi_y - \frac{g}{\omega^2} = 0$$

Substituting $\cos \phi_y$,

$$\left(\frac{v_0 \sin \theta}{\omega} \sqrt{r^2 + 1} \right) \left(\frac{1}{\sqrt{r^2 + 1}} \right) - \frac{g}{\omega^2} = 0$$

$$\frac{v_0 \sin \theta}{\omega} - \frac{g}{\omega^2} = 0$$

Hence,

$$\boxed{\omega = \frac{g}{v_0 \sin \theta}}$$