

Solutions - Chapter 3

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Problem 3.1

a)

$$[\hat{A}, \hat{B} + \hat{C}] = \hat{A}(\hat{B} + \hat{C}) - (\hat{B} + \hat{C})\hat{A} = \hat{A}\hat{B} - \hat{B}\hat{A} + \hat{A}\hat{C} - \hat{C}\hat{A} = [\hat{A}, \hat{B}] + [\hat{A}, \hat{C}]$$

b)

$$i[\hat{A}, \hat{B}\hat{C}] = \hat{A}\hat{B}\hat{C} - \hat{B}\hat{C}\hat{A} = \hat{A}\hat{B}\hat{C} - \hat{B}\hat{A}\hat{C} + \hat{B}\hat{A}\hat{C} - \hat{B}\hat{C}\hat{A} = \hat{B}[\hat{A}, \hat{C}] + [\hat{A}, \hat{B}]\hat{C}$$

Problem 3.2

Eigenstate problem:

$$\hat{S}_n |\mu\rangle = \mu \frac{\hbar}{2} |\mu\rangle$$

$$\hat{S}_n = S_x \sin \theta \cos \phi + S_y \sin \theta \sin \phi + S_z \cos \theta$$

$$\begin{aligned} &= \frac{\hbar}{2} \left[\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \sin \theta \cos \phi + \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \sin \theta \sin \phi + \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \cos \theta \right] \\ &= \frac{\hbar}{2} \begin{pmatrix} \cos \theta & \sin \theta (\cos \phi - i \sin \phi) \\ \sin \theta (\cos \phi + i \sin \phi) & -\cos \theta \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} \cos \theta & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta \end{pmatrix} \end{aligned}$$

Matrix form:

$$\frac{\hbar}{2} \begin{pmatrix} \cos \theta & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} \langle +\mathbf{z} | \mu \rangle \\ \langle -\mathbf{z} | \mu \rangle \end{pmatrix} = \mu \frac{\hbar}{2} \begin{pmatrix} \langle +\mathbf{z} | \mu \rangle \\ \langle -\mathbf{z} | \mu \rangle \end{pmatrix}$$

$$\begin{pmatrix} \cos \theta - \mu & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta - \mu \end{pmatrix} \begin{pmatrix} \langle +\mathbf{z} | \mu \rangle \\ \langle -\mathbf{z} | \mu \rangle \end{pmatrix} = 0$$

$$\begin{vmatrix} \cos \theta - \mu & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta - \mu \end{vmatrix} = \mu^2 - \cos^2 \theta - \sin^2 \theta = 0$$

Eigenvalues:

$$\mu = \pm 1$$

$$\begin{pmatrix} \cos \theta \mp 1 & e^{-i\phi} \sin \theta \\ e^{i\phi} \sin \theta & -\cos \theta \mp 1 \end{pmatrix} \begin{pmatrix} \langle +\mathbf{z} | \pm \mathbf{n} \rangle \\ \langle -\mathbf{z} | \pm \mathbf{n} \rangle \end{pmatrix} = 0$$

Equation:

$$(\cos \theta \mp 1) \langle +\mathbf{z} | \pm \mathbf{n} \rangle + e^{-i\phi} \sin \theta \langle -\mathbf{z} | \pm \mathbf{n} \rangle = 0$$

Normalization:

$$|\langle +\mathbf{z} | \pm \mathbf{n} \rangle|^2 + |\langle -\mathbf{z} | \pm \mathbf{n} \rangle|^2 = 1$$

$$|\langle +\mathbf{z} | \pm \mathbf{n} \rangle|^2 + \frac{(\cos \theta \mp 1)^2}{\sin^2 \theta} |\langle +\mathbf{z} | \pm \mathbf{n} \rangle|^2 = 1$$

$$|\langle +\mathbf{z} | \pm \mathbf{n} \rangle|^2 = \frac{\sin^2 \theta}{\sin^2 \theta + (\cos \theta \mp 1)^2} = \frac{\sin^2 \theta}{2 \mp 2 \cos \theta} = \frac{(1 - \cos \theta)(1 + \cos \theta)}{2(1 \mp \cos \theta)}$$

$$|\langle +\mathbf{z} | + \mathbf{n} \rangle| = \sqrt{\frac{1 + \cos \theta}{2}} = \cos \frac{\theta}{2}$$

$$|\langle +\mathbf{z} | - \mathbf{n} \rangle| = \sqrt{\frac{1 - \cos \theta}{2}} = \sin \frac{\theta}{2}$$

$$|\langle -\mathbf{z} | + \mathbf{n} \rangle| = e^{i\phi} \sin \frac{\theta}{2}$$

$$|\langle -\mathbf{z} | - \mathbf{n} \rangle| = -e^{i\phi} \cos \frac{\theta}{2}$$

Eigenstates:

$$|+\mathbf{n}\rangle = \cos \frac{\theta}{2} |+\mathbf{z}\rangle + e^{i\phi} \sin \frac{\theta}{2} |-\mathbf{z}\rangle$$

$$|-\mathbf{n}\rangle = \sin \frac{\theta}{2} |+\mathbf{z}\rangle - e^{i\phi} \cos \frac{\theta}{2} |-\mathbf{z}\rangle$$

Problem 3.3

$$\sigma_1^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\sigma_2^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\sigma_3^2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\sigma_1 \sigma_2 + \sigma_2 \sigma_1 = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} + \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} = 0$$

$$\sigma_1\sigma_3 + \sigma_3\sigma_1 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = 0$$

$$\sigma_2\sigma_3 + \sigma_3\sigma_2 = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} + \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix} = 0$$

$$\{\sigma_i, \sigma_j\} = 2\delta_{ij}I$$

Problem 3.4

a)

$$\boldsymbol{\sigma} \times \boldsymbol{\sigma} = (\sigma_x \mathbf{i} + \sigma_y \mathbf{j} + \sigma_z \mathbf{k}) \times (\sigma_x \mathbf{i} + \sigma_y \mathbf{j} + \sigma_z \mathbf{k})$$

$$= (\sigma_y\sigma_z - \sigma_z\sigma_y)\mathbf{i} + (\sigma_z\sigma_x - \sigma_x\sigma_z)\mathbf{j} + (\sigma_x\sigma_y - \sigma_y\sigma_x)\mathbf{k}$$

$$[\sigma_y, \sigma_z] = 2i\sigma_x$$

$$[\sigma_z, \sigma_x] = 2i\sigma_y$$

$$[\sigma_x, \sigma_y] = 2i\sigma_z$$

$$\boldsymbol{\sigma} \times \boldsymbol{\sigma} = 2i\boldsymbol{\sigma}$$

b)

$$\boldsymbol{\sigma} \cdot \mathbf{a} \boldsymbol{\sigma} \cdot \mathbf{b} = (a_x\sigma_x + a_y\sigma_y + a_z\sigma_z)(b_x\sigma_x + b_y\sigma_y + b_z\sigma_z)$$

$$= (a_xb_x + a_yb_y + a_zb_z)I + a_xb_y\sigma_x\sigma_y + a_xb_z\sigma_x\sigma_z + a_yb_x\sigma_y\sigma_x + a_yb_z\sigma_y\sigma_z + a_zb_x\sigma_z\sigma_x + a_zb_y\sigma_z\sigma_y$$

$$= \mathbf{a} \cdot \mathbf{b}I + i\sigma_x(a_yb_z - a_zb_y) - i\sigma_y(a_xb_z - a_zb_x) + i\sigma_z(a_xb_y - a_yb_x)$$

$$\boldsymbol{\sigma} \cdot \mathbf{a} \boldsymbol{\sigma} \cdot \mathbf{b} = \mathbf{a} \cdot \mathbf{b}I + i\boldsymbol{\sigma} \cdot (\mathbf{a} \times \mathbf{b})$$

Problem 3.5

a)

$$\hat{R}(\theta \mathbf{j}) = e^{-i\hat{S}_y\theta/\hbar} = 1 - \left(\frac{i\theta}{\hbar}\right)\hat{S}_y + \frac{1}{2!}\left(\frac{i\theta}{\hbar}\right)^2\hat{S}_y^2 - \frac{1}{3!}\left(\frac{i\theta}{\hbar}\right)^3\hat{S}_y^3 + \dots$$

$$\hat{S}_y^2 = I$$

$$\hat{R}(\theta \mathbf{j}) = 1 - \frac{1}{2!}\left(\frac{\theta}{2}\right)^2 + \frac{1}{4!}\left(\frac{\theta}{2}\right)^4 + \dots$$

$$+ i\sigma_y \left[\left(\frac{\theta}{2}\right) - \frac{1}{3!}\left(\frac{\theta}{2}\right)^3 + \dots \right]$$

$$\hat{R}(\theta \mathbf{j}) = \cos \frac{\theta}{2} + \frac{2i}{\hbar} \hat{S}_y \sin \frac{\theta}{2}$$

b)

$$\hat{R}(\theta \mathbf{j}) \xrightarrow{s_z} \begin{pmatrix} \cos(\theta/2) & 0 \\ 0 & \cos(\theta/2) \end{pmatrix} + \begin{pmatrix} 0 & \sin(\theta/2) \\ -\sin(\theta/2) & 0 \end{pmatrix}$$

$$\hat{R}(\theta \mathbf{j}) |+\mathbf{z}\rangle = \begin{pmatrix} \cos(\theta/2) & \sin(\theta/2) \\ -\sin(\theta/2) & \cos(\theta/2) \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$\phi = 0$:

$$|+\mathbf{n}\rangle = \cos \frac{\theta}{2} |+\mathbf{z}\rangle + \sin \frac{\theta}{2} |-\mathbf{z}\rangle$$

Problem 3.6

$$\hat{J}_- |j, m\rangle = c_- \hbar |j, m-1\rangle$$

$$\hat{J}_+ \hat{J}_- = (\hat{J}_x + i\hat{J}_y)(\hat{J}_x - i\hat{J}_y) = \hat{J}_x^2 + \hat{J}_y^2 - i[\hat{J}_x, \hat{J}_y] = \mathbf{\hat{J}}^2 - \hat{J}_z^2 + \hbar \hat{J}_z$$

$$\langle j, m | \hat{J}_+ \hat{J}_- |j, m\rangle = c_-^* c_- \hbar^2 \langle j, m-1 | j, m-1 \rangle$$

$$\langle j, m | \mathbf{\hat{J}}^2 - \hat{J}_z^2 + \hbar \hat{J}_z |j, m\rangle = [j(j+1) - m^2 + m] \hbar^2 \langle j, m | j, m \rangle$$

$$c_- = \sqrt{j(j+1) - m(m-1)} |j, m-1\rangle$$

Problem 3.7

$$(\langle \alpha | + \lambda^* \langle \beta |)(|\alpha\rangle + \lambda |\beta\rangle) \geq 0$$

$$\langle \alpha | \alpha \rangle + \lambda^* \langle \beta | \alpha \rangle + \lambda \langle \alpha | \beta \rangle + \lambda^* \lambda \langle \beta | \beta \rangle \geq 0$$

Choose:

$$\lambda = -\frac{\langle \beta | \alpha \rangle}{\langle \beta | \beta \rangle}$$

$$\langle \alpha | \alpha \rangle - \frac{\langle \alpha | \beta \rangle \langle \beta | \alpha \rangle}{\langle \beta | \beta \rangle} - \frac{\langle \beta | \alpha \rangle \langle \alpha | \beta \rangle}{\langle \beta | \beta \rangle} + \frac{\langle \alpha | \beta \rangle \langle \beta | \alpha \rangle}{\langle \beta | \beta \rangle} = 0$$

$$\langle \alpha | \alpha \rangle \geq \frac{\langle \beta | \alpha \rangle \langle \alpha | \beta \rangle}{\langle \beta | \beta \rangle}$$

Schwarz inequality:

$$\langle \alpha | \alpha \rangle \langle \beta | \beta \rangle \geq |\langle \alpha | \beta \rangle|^2$$

Problem 3.8

$$[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A} = i\hat{C}$$

Hermitian:

$$\langle \alpha | A | \beta \rangle^* = \langle \beta | A | \alpha \rangle$$

$$\langle \alpha | AB - BA | \beta \rangle^* = \langle \alpha | AB | \beta \rangle^* - \langle \alpha | BA | \beta \rangle^* = \langle \beta | BA | \alpha \rangle - \langle \beta | AB | \alpha \rangle = \langle \beta | BA - AB | \alpha \rangle$$

$$BA - AB = -iC$$

$$\langle \alpha | iC | \beta \rangle^* = -i \langle \alpha | C | \beta \rangle = \langle \alpha | -iC | \beta \rangle$$

C is Hermitian:

$$\langle \alpha | C | \beta \rangle^* = \langle \beta | C | \alpha \rangle$$

Problem 3.9

Eigenstate of $\hat{S}_z$: $|+\mathbf{z}\rangle$

$$\Delta S_x = \sqrt{\langle S_x^2 \rangle - \langle S_x \rangle^2} = \frac{\hbar}{2}$$

$$\langle S_x \rangle = \langle +\mathbf{z} | S_x | +\mathbf{z} \rangle = 0$$

$$\langle S_x^2 \rangle = \langle +\mathbf{z} | S_x^2 | +\mathbf{z} \rangle = \left(\frac{\hbar}{2}\right)^2$$

$$\Delta S_y = \sqrt{\langle S_y^2 \rangle - \langle S_y \rangle^2} = \frac{\hbar}{2}$$

$$\langle S_y \rangle = \langle +\mathbf{z} | S_y | +\mathbf{z} \rangle = 0$$

$$\langle S_y^2 \rangle = \langle +\mathbf{z} | S_y^2 | +\mathbf{z} \rangle = \left(\frac{\hbar}{2}\right)^2$$

$$\langle S_z \rangle = \langle +\mathbf{z} | S_z | +\mathbf{z} \rangle = \frac{\hbar}{2}$$

$$\Delta S_x \Delta S_y \geq \frac{\hbar |\langle S_z \rangle|}{2}$$

$$\left(\frac{\hbar}{2}\right) \left(\frac{\hbar}{2}\right) \geq \left(\frac{\hbar}{2}\right) \left(\frac{\hbar}{2}\right)$$

Eigenstate of $\hat{S}_x$: $|+\mathbf{x}\rangle$

$$\Delta S_x = \sqrt{\langle S_x^2 \rangle - \langle S_x \rangle^2} = 0$$

$$\begin{aligned}
\langle S_x \rangle &= \langle +\mathbf{x} | S_x | +\mathbf{x} \rangle = \frac{\hbar}{2} \\
\langle S_x^2 \rangle &= \langle +\mathbf{x} | S_x^2 | +\mathbf{x} \rangle = \left(\frac{\hbar}{2} \right)^2 \\
\Delta S_y &= \sqrt{\langle S_y^2 \rangle - \langle S_y \rangle^2} = \frac{\hbar}{2} \\
\langle S_y \rangle &= \langle +\mathbf{x} | S_y | +\mathbf{x} \rangle = 0 \\
\langle S_y^2 \rangle &= \langle +\mathbf{x} | S_y^2 | +\mathbf{x} \rangle = \left(\frac{\hbar}{2} \right)^2 \\
\langle S_z \rangle &= \langle +\mathbf{x} | S_z | +\mathbf{x} \rangle = 0 \\
\Delta S_x \Delta S_y &\geq \frac{\hbar |\langle S_z \rangle|}{2} \\
0 &\geq 0
\end{aligned}$$

Problem 3.10

$$\begin{aligned}
S_x &\xrightarrow{S_z} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \\
S_y &\xrightarrow{S_z} \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \\
S_x &\xrightarrow{S_z} \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\
[\hat{S}_x, \hat{S}_y] &= i\hbar \hat{S}_z \\
S_x S_y - S_y S_x &= \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} - \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \\
&= \left(\frac{\hbar}{2} \right)^2 \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} - \left(\frac{\hbar}{2} \right)^2 \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} = \frac{i\hbar^2}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = i\hbar \hat{S}_z
\end{aligned}$$

Problem 3.11

Instead of inserting the identity element connecting the two bases, we can use a cyclic substitution $x \rightarrow y, y \rightarrow z, z \rightarrow x$:

$$\hat{S}_y \xrightarrow{S_y} \left(\frac{\hbar}{2} \right) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\hat{S}_z \xrightarrow{\hat{S}_y} \left(\frac{\hbar}{2}\right) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\hat{S}_x \xrightarrow{\hat{S}_y} \left(\frac{\hbar}{2}\right) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

Problem 3.12

$$\hat{S}_z |+\mathbf{z}\rangle = \frac{\hbar}{2} |+\mathbf{z}\rangle$$

$$\hat{S}_z |-\mathbf{z}\rangle = -\frac{\hbar}{2} |-\mathbf{z}\rangle$$

$$\hat{S}_z = \frac{\hbar}{2} |+\mathbf{z}\rangle \langle +\mathbf{z}| - \frac{\hbar}{2} |-\mathbf{z}\rangle \langle -\mathbf{z}|$$

$$\hat{S}_+ |+\mathbf{z}\rangle = 0$$

$$\hat{S}_+ |-\mathbf{z}\rangle = \hbar |+\mathbf{z}\rangle$$

$$\hat{S}_- |+\mathbf{z}\rangle = \hbar |-\mathbf{z}\rangle$$

$$\hat{S}_- |-\mathbf{z}\rangle = 0$$

$$\hat{S}_+ = \hbar |+\mathbf{z}\rangle \langle -\mathbf{z}|$$

$$\hat{S}_- = \hbar |-\mathbf{z}\rangle \langle +\mathbf{z}|$$

Problem 3.13

$$\hat{J}_x \xrightarrow{\hat{J}_z} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\hat{J}_y \xrightarrow{\hat{J}_z} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\hat{J}_z \xrightarrow{\hat{J}_z} \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$[\hat{J}_x, \hat{J}_y] = \hat{J}_x \hat{J}_y - \hat{J}_y \hat{J}_x$$

$$\frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} - \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$= i\hbar^2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} = i\hbar \hat{J}_z$$

Problem 3.14

Angular Momentum (spin-1: $j = 1$):

$$\hat{J}_z |j, m\rangle = m\hbar |j, m\rangle$$

$$\hat{J}_z |1, 1\rangle = \hbar |1, 1\rangle$$

$$\hat{J}_z |1, 0\rangle = 0$$

$$\hat{J}_z |1, -1\rangle = -\hbar |1, -1\rangle$$

$$\hat{J}_z = \hbar |1, 1\rangle \langle 1, 1| - \hbar |1, -1\rangle \langle 1, -1| \xrightarrow{J_z} \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$\hat{J}_+ |1, 1\rangle = 0$$

$$\hat{J}_+ |1, 0\rangle = \sqrt{2}\hbar |1, 1\rangle$$

$$\hat{J}_+ |1, -1\rangle = \sqrt{2}\hbar |1, 0\rangle$$

$$\hat{J}_+ = \sqrt{2}\hbar(|1, 1\rangle \langle 1, 0| + |1, 0\rangle \langle 1, -1|) \xrightarrow{J_+} \sqrt{2}\hbar \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\hat{J}_- |1, 1\rangle = \sqrt{2}\hbar |1, 0\rangle$$

$$\hat{J}_- |1, 0\rangle = \sqrt{2}\hbar |1, -1\rangle$$

$$\hat{J}_- |1, -1\rangle = 0$$

$$\hat{J}_- = \sqrt{2}\hbar(|1, 0\rangle \langle 1, 1| + |1, -1\rangle \langle 1, 0|) \xrightarrow{J_-} \sqrt{2}\hbar \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\hat{J}_x = \frac{J_+ + J_-}{2}$$

$$\hat{J}_y = \frac{J_+ - J_-}{2i}$$

$$\hat{J}_x \xrightarrow{J_x} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\hat{J}_y \xrightarrow{J_z} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix}$$

Problem 3.15

$$\hat{S}_x |1, \mu\rangle_x = \mu \hbar |1, \mu\rangle_x$$

$$\frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \mu \hbar \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

Eigenvalues: $\mu = 1, 0, -1$

$$\begin{pmatrix} -\mu & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\mu & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & -\mu \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$

$\mu = 1$:

$$-a + \frac{1}{\sqrt{2}}b = 0$$

$$\frac{1}{\sqrt{2}}b - c = 0$$

$$b = \sqrt{2}a$$

$$c = a$$

Normalization:

$$a^2 + 2a^2 + a^2 = 1$$

$$a = \frac{1}{2}$$

$$|1, 1\rangle_x = \frac{1}{2} |1, 1\rangle + \frac{\sqrt{2}}{2} |1, 0\rangle + \frac{1}{2} |1, -1\rangle$$

$\mu = 0$:

$$\frac{1}{\sqrt{2}}b = 0$$

$$\frac{1}{\sqrt{2}}a + \frac{1}{\sqrt{2}}c = 0$$

$$b = 0$$

$$c = -a$$

Normalization:

$$a^2 + 0 + a^2 = 1$$

$$a = \frac{\sqrt{2}}{2}$$

$$|1, 0\rangle_x = \frac{\sqrt{2}}{2} |1, 1\rangle - \frac{\sqrt{2}}{2} |1, -1\rangle$$

$\mu = -1$:

$$a + \frac{1}{\sqrt{2}}b = 0$$

$$\frac{1}{\sqrt{2}}b + c = 0$$

$$b = -\sqrt{2}a$$

$$c = a$$

Normalization:

$$a^2 + 2a^2 + a^2 = 1$$

$$a = \frac{1}{2}$$

$$|1, -1\rangle_x = \frac{1}{2} |1, 1\rangle - \frac{\sqrt{2}}{2} |1, 0\rangle + \frac{1}{2} |1, -1\rangle$$

Problem 3.16

$$P = |\langle 1, 0 |_x |1, 1\rangle|^2 = \frac{1}{2}$$

$$\langle 1, 0 |_x = \frac{\sqrt{2}}{2} \langle 1, 1| - \frac{\sqrt{2}}{2} \langle 1, -1|$$

$$\langle 1, 0 |_x |1, 1\rangle = \frac{\sqrt{2}}{2} \langle 1, 1|1, 1\rangle - \frac{\sqrt{2}}{2} \langle 1, -1|1, 1\rangle = \frac{\sqrt{2}}{2}$$

Problem 3.17

$$|\psi\rangle \xrightarrow{S_z} \frac{1}{\sqrt{14}} \begin{pmatrix} 1 \\ 2 \\ 3i \end{pmatrix}$$

a)

$$P(S_z = \hbar) = |\langle 1, 1 | \psi \rangle|^2 = \frac{1}{14}$$

$$P(S_z = 0) = |\langle 1, 0 | \psi \rangle|^2 = \frac{2}{7}$$

$$P(S_z = -\hbar) = |\langle 1, -1 | \psi \rangle|^2 = \frac{9}{14}$$

$$\langle S_z \rangle = P(S_z = \hbar)(\hbar) + P(S_z = 0)(0) + P(S_z = -\hbar)(-\hbar) = -\frac{4}{7}\hbar$$

b)

$$\begin{aligned}\langle S_x \rangle &= \langle \psi | S_x | \psi \rangle \\ &= \frac{1}{\sqrt{14}} \begin{pmatrix} 1 & 2 & -3i \end{pmatrix} \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \frac{1}{\sqrt{14}} \begin{pmatrix} 1 \\ 2 \\ 3i \end{pmatrix} = \frac{2}{7\sqrt{2}} \hbar\end{aligned}$$

c)

$$\begin{aligned}P(S_x = \hbar) &= |\langle 1, 1_x | \psi \rangle|^2 \\ \langle 1, 1 |_x &= \frac{1}{2} \langle 1, 1 | + \frac{\sqrt{2}}{2} \langle 1, 0 | + \frac{1}{2} \langle 1, -1 | \\ |\psi\rangle &= \frac{1}{\sqrt{14}} |1, 1\rangle + \frac{2}{\sqrt{14}} |1, 0\rangle + \frac{3i}{\sqrt{14}} |1, -1\rangle \\ \langle 1, 1_x | \psi \rangle &= \frac{1}{2\sqrt{14}} + \frac{2\sqrt{2}}{2\sqrt{14}} + \frac{3i}{2\sqrt{14}} = \frac{1 + 2\sqrt{2} + 3i}{2\sqrt{14}} \\ P(S_x = \hbar) &= |\langle 1, 1_x | \psi \rangle|^2 = \left(\frac{1 + 2\sqrt{2}}{2\sqrt{14}} \right)^2 + \left(\frac{3}{2\sqrt{14}} \right)^2 = \frac{1 + 4\sqrt{2} + 8 + 9}{4(14)} = \frac{9 + 2\sqrt{2}}{28}\end{aligned}$$

Problem 3.18

$$\begin{aligned}\hat{S}_n |\mu\rangle &= \mu \hbar |\mu\rangle \\ \hat{S}_n &= S_x \sin \theta \cos \phi + S_y \sin \theta \sin \phi + S_z \cos \theta \\ &= \left[\frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \sin \theta \cos \phi + \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \sin \theta \sin \phi + \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix} \cos \theta \right] \\ &= \hbar \begin{pmatrix} \cos \theta & \frac{\sin \theta \cos \phi - i \sin \theta \sin \phi}{\sqrt{2}} & 0 \\ \frac{\sin \theta \cos \phi + i \sin \theta \sin \phi}{\sqrt{2}} & 0 & \frac{\sin \theta \cos \phi - i \sin \theta \sin \phi}{\sqrt{2}} \\ 0 & \frac{\sin \theta \cos \phi + i \sin \theta \sin \phi}{\sqrt{2}} & -\cos \theta \end{pmatrix} \\ &= \hbar \begin{pmatrix} \cos \theta & \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} & 0 \\ \frac{e^{i\phi} \sin \theta}{\sqrt{2}} & 0 & \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} \\ 0 & \frac{e^{i\phi} \sin \theta}{\sqrt{2}} & -\cos \theta \end{pmatrix} \\ &= \hbar \begin{pmatrix} \cos \theta & \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} & 0 \\ \frac{e^{i\phi} \sin \theta}{\sqrt{2}} & 0 & \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} \\ 0 & \frac{e^{i\phi} \sin \theta}{\sqrt{2}} & -\cos \theta \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \mu \hbar \begin{pmatrix} a \\ b \\ c \end{pmatrix}\end{aligned}$$

$$\begin{pmatrix} \cos \theta - \mu & \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} & 0 \\ \frac{e^{i\phi} \sin \theta}{\sqrt{2}} & -\mu & \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} \\ 0 & \frac{e^{i\phi} \sin \theta}{\sqrt{2}} & -\cos \theta - \mu \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$

Eigenvalues:

$$(\cos \theta - \mu) \left[(-\mu)(-\cos \theta - \mu) - \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} \frac{e^{i\phi} \sin \theta}{\sqrt{2}} \right] - \frac{e^{-i\phi} \sin \theta}{\sqrt{2}} \left[\frac{e^{i\phi} \sin \theta}{\sqrt{2}} (-\cos \theta - \mu) \right] = 0$$

$$(\cos \theta - \mu) \left[(-\mu)(-\cos \theta - \mu) - \frac{\sin^2 \theta}{2} \right] - \frac{\sin^2 \theta}{2} (-\cos \theta - \mu) = 0$$

$$(-\mu)(\mu^2 - \cos^2 \theta) - \frac{\sin^2 \theta}{2}(\cos \theta - \mu) + \frac{\sin^2 \theta}{2}(\cos \theta + \mu) = 0$$

$$(-\mu)(\mu^2 - \cos^2 \theta) - \frac{\sin^2 \theta}{2}(\cos \theta - \mu) + \frac{\sin^2 \theta}{2}(\cos \theta + \mu) = 0$$

$$(-\mu)(\mu^2 - \cos^2 \theta - \sin^2 \theta) = 0$$

$$\mu = 1, 0, -1$$

$\mu = 1$:

$$(\cos \theta - 1)a + \frac{e^{-i\phi} \sin \theta}{\sqrt{2}}b = 0$$

$$\frac{e^{i\phi} \sin \theta}{\sqrt{2}}b - (\cos \theta + 1)c = 0$$

$$c = \frac{1 - \cos \theta}{1 + \cos \theta}a$$

$$b = \frac{e^{i\phi}(1 - \cos \theta)\sqrt{2}}{\sin \theta}a$$

Normalization:

$$a^2 + \frac{2(1 - \cos \theta)^2}{\sin^2 \theta}a^2 + \frac{(1 - \cos \theta)^2}{(1 + \cos \theta)^2}a^2 = 1$$

$$a = \frac{1 + \cos \theta}{2} = \cos^2 \left(\frac{\theta}{2} \right)$$

$$|1, 1\rangle_n = \cos^2 \left(\frac{\theta}{2} \right) |1, 1\rangle + \frac{e^{i\phi} \sin \theta \sqrt{2}}{2} |1, 0\rangle + \sin^2 \left(\frac{\theta}{2} \right) |1, -1\rangle$$

$\mu = 0$:

$$(\cos \theta)a + \frac{e^{-i\phi} \sin \theta}{\sqrt{2}}b = 0$$

$$\frac{e^{i\phi} \sin \theta}{\sqrt{2}}b - (\cos \theta)c = 0$$

$$b = -\frac{e^{i\phi} \cos \theta \sqrt{2}}{\sin \theta}a$$

$$c = -a$$

Normalization:

$$a^2 + \frac{2 \cos^2 \theta}{\sin^2 \theta}a^2 + a^2 = 1$$

$$a = \frac{\sin \theta \sqrt{2}}{2}$$

$$|1, 0\rangle_n = \frac{\sin \theta \sqrt{2}}{2} |1, 1\rangle - e^{i\phi} \cos \theta |1, 0\rangle - \frac{\sin \theta \sqrt{2}}{2} |1, -1\rangle$$

$\mu = -1$:

$$(\cos \theta + 1)a + \frac{e^{-i\phi} \sin \theta}{\sqrt{2}}b = 0$$

$$\frac{e^{i\phi} \sin \theta}{\sqrt{2}}b - (\cos \theta - 1)c = 0$$

$$c = \frac{1 + \cos \theta}{1 - \cos \theta}a$$

$$b = -\frac{e^{i\phi}(1 + \cos \theta)\sqrt{2}}{\sin \theta}a$$

Normalization:

$$a^2 + \frac{2(1 + \cos \theta)^2}{\sin^2 \theta}a^2 + \frac{(1 + \cos \theta)^2}{(1 - \cos \theta)^2}a^2 = 1$$

$$a = \frac{1 - \cos \theta}{2} = \sin^2 \left(\frac{\theta}{2} \right)$$

$$|1, -1\rangle_n = \sin^2 \left(\frac{\theta}{2} \right) |1, 1\rangle - \frac{e^{i\phi} \sin \theta \sqrt{2}}{2} |1, 0\rangle + \cos^2 \left(\frac{\theta}{2} \right) |1, -1\rangle$$

Problem 3.19

$$\hat{R}(\theta \mathbf{j}) = e^{-i\hat{S}_y \theta / \hbar} = 1 + \left(-\frac{i\theta}{\hbar} \right) \hat{S}_y + \frac{1}{2!} \left(-\frac{i\theta}{\hbar} \right)^2 \hat{S}_y^2 + \frac{1}{3!} \left(-\frac{i\theta}{\hbar} \right)^3 \hat{S}_y^3 + \dots$$

$$\begin{aligned}
\hat{S}_y &= \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix} \\
\hat{S}_y^2 &= \left(\frac{\hbar}{\sqrt{2}}\right)^2 \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \\
\hat{S}_y^3 &= \left(\frac{\hbar}{\sqrt{2}}\right)^3 \begin{pmatrix} 0 & -2i & 0 \\ 2i & 0 & -2i \\ 0 & 2i & 0 \end{pmatrix} = \hbar^2 \hat{S}_y \\
\hat{S}_y^4 &= \left(\frac{\hbar}{\sqrt{2}}\right)^4 \begin{pmatrix} 2 & 0 & -2 \\ 0 & 4 & 0 \\ -2 & 0 & 2 \end{pmatrix} = \hbar^2 \hat{S}_y^2 \\
\hat{R}(\theta \mathbf{j}) &= 1 + \frac{1}{2!} \left(-\frac{i\theta}{\hbar}\right)^2 \hat{S}_y^2 + \frac{1}{4!} \left(-\frac{i\theta}{\hbar}\right)^4 \hat{S}_y^4 + \dots + \left(-\frac{i\theta}{\hbar}\right) \hat{S}_y + \frac{1}{3!} \left(-\frac{i\theta}{\hbar}\right)^3 \hat{S}_y^3 \\
&= 1 + \frac{S_y^2}{2} \left[-\frac{1}{2!} (\theta)^2 + \frac{1}{4!} (\theta)^4 - \dots\right] + \dots + \frac{-iS_y}{\sqrt{2}} \left[(\theta) - \frac{1}{3!} (\theta)^3 + \dots\right] \\
&= 1 + \frac{S_y^2}{2} (\cos \theta - 1) - \frac{iS_y}{\sqrt{2}} \sin \theta \\
&= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \begin{pmatrix} \frac{\cos \theta - 1}{2} & 0 & \frac{1 - \cos \theta}{2} \\ 0 & \cos \theta - 1 & 0 \\ \frac{1 - \cos \theta}{2} & 0 & \frac{1 - \cos \theta}{2} \end{pmatrix} + \begin{pmatrix} 0 & -\frac{\sin \theta}{\sqrt{2}} & 0 \\ \frac{\sin \theta}{\sqrt{2}} & 0 & -\frac{\sin \theta}{\sqrt{2}} \\ 0 & \frac{\sin \theta}{\sqrt{2}} & 0 \end{pmatrix} \\
\hat{R}(\theta \mathbf{j}) &= \begin{pmatrix} \frac{1 + \cos \theta}{2} & -\frac{\sin \theta}{\sqrt{2}} & \frac{1 - \cos \theta}{2} \\ \frac{\sin \theta}{\sqrt{2}} & \cos \theta & -\frac{\sin \theta}{\sqrt{2}} \\ \frac{1 - \cos \theta}{2} & \frac{\sin \theta}{\sqrt{2}} & \frac{1 + \cos \theta}{2} \end{pmatrix} \\
\hat{R}(\theta \mathbf{j}) |1, 1\rangle &= \cos^2 \left(\frac{\theta}{2}\right) |1, 1\rangle + \frac{\sin \theta \sqrt{2}}{2} |1, 0\rangle + \sin^2 \left(\frac{\theta}{2}\right) |1, -1\rangle
\end{aligned}$$

Problem 3.20

a)

$$f = |\langle S_n = \hbar | S_z = \hbar \rangle|^2 |\langle S_z = -\hbar | S_n = \hbar \rangle|^2 = |\langle 1, 1 |_n |1, 1\rangle|^2 |\langle 1, -1 | |1, 1\rangle_n|^2$$

$$|1, 1\rangle_n = \cos^2 \left(\frac{\theta}{2}\right) |1, 1\rangle + \frac{\sin \theta \sqrt{2}}{2} |1, 0\rangle + \sin^2 \left(\frac{\theta}{2}\right) |1, -1\rangle$$

$$\langle 1, 1 |_n = \cos^2 \left(\frac{\theta}{2}\right) \langle 1, 1| + \frac{\sin \theta \sqrt{2}}{2} \langle 1, 0| + \sin^2 \left(\frac{\theta}{2}\right) \langle 1, -1|$$

$$\langle 1, 1|_n|1, 1\rangle = \cos^2\left(\frac{\theta}{2}\right)$$

$$\langle 1, -1||1, 1\rangle_n = \sin^2\left(\frac{\theta}{2}\right)$$

$$f = \sin^4\left(\frac{\theta}{2}\right) \cos^4\left(\frac{\theta}{2}\right) = \frac{\sin^4\theta}{16}$$

b)

$$\theta = \pm\frac{\pi}{2}$$

$$f_{max} = \frac{1}{16}$$

c)

$$f = |\langle 1, -1|1, 1\rangle|^2 = 0$$

Last $SG\mathbf{z}$ device transmits particles with $S_z = 0$ only:

a)

$$f = |\langle 1, 1|_n|1, 1\rangle|^2 |\langle 1, 0||1, 1\rangle_n|^2$$

$$\langle 1, 1|_n|1, 1\rangle = \cos^2\left(\frac{\theta}{2}\right)$$

$$\langle 1, 0||1, 1\rangle_n = \frac{\sin\theta\sqrt{2}}{2}$$

$$f = \cos^4\left(\frac{\theta}{2}\right) \frac{\sin^2\theta}{2} = \frac{\sin^2\theta(1+\cos\theta)^2}{8}$$

b)

$$\frac{d}{d\theta} [\sin^2\theta(1+\cos\theta)^2] = 2\sin\theta\cos\theta(1+\cos\theta)^2 + 2\sin^2\theta(1+\cos\theta)(-\sin\theta) = 0$$

$$\sin\theta = 0$$

$$1 + \cos\theta = 0:$$

$$\cos\theta(1+\cos\theta) - \sin^2\theta = 2\cos^2\theta + \cos\theta - 1 = 0$$

$$(2\cos\theta - 1)(\cos\theta + 1) = 0$$

$$\cos\theta = \frac{1}{2}$$

$$\theta = \pm\frac{\pi}{3}$$

$$f_{max} = \frac{27}{128}$$

c)

$$f = |\langle 1, 0 | 1, 1 \rangle|^2 = 0$$

Problem 3.21

$$J_z = m\hbar$$

$$\mathbf{J} = \sqrt{j(j+1)}\hbar$$

$$\cos \theta = \frac{m}{\sqrt{j(j+1)}}$$

a) spin- $\frac{1}{2}$

$$\cos \theta = \frac{1/2}{\sqrt{(1/2)(1/2+1)}} = \frac{\sqrt{3}}{3}$$

$$\theta = \arccos \frac{\sqrt{3}}{3}$$

b) spin-1

$$\cos \theta = \frac{1}{\sqrt{(1)(1+1)}} = \frac{\sqrt{2}}{2}$$

$$\theta = \frac{\pi}{4}$$

c) macroscopic spinning top

$$L_z = \mathbf{L}$$

$$\theta = 0$$

Problem 3.22

$$|\psi\rangle = \sum_{a,b} c_{a,b} |a, b\rangle$$

$$\hat{A}\hat{B}|\psi\rangle = \sum_{a,b} c_{a,b} \hat{A}\hat{B}|a, b\rangle = \sum_{a,b} c_{a,b} \hat{A}b|a, b\rangle = \sum_{a,b} c_{a,b} ab|a, b\rangle$$

$$\hat{B}\hat{A}|\psi\rangle = \sum_{a,b} c_{a,b} \hat{B}\hat{A}|a, b\rangle = \sum_{a,b} c_{a,b} \hat{B}a|a, b\rangle = \sum_{a,b} c_{a,b} ba|a, b\rangle$$

$$\hat{A}\hat{B} = \hat{B}\hat{A}$$

$$[\hat{A}, \hat{B}] = 0$$